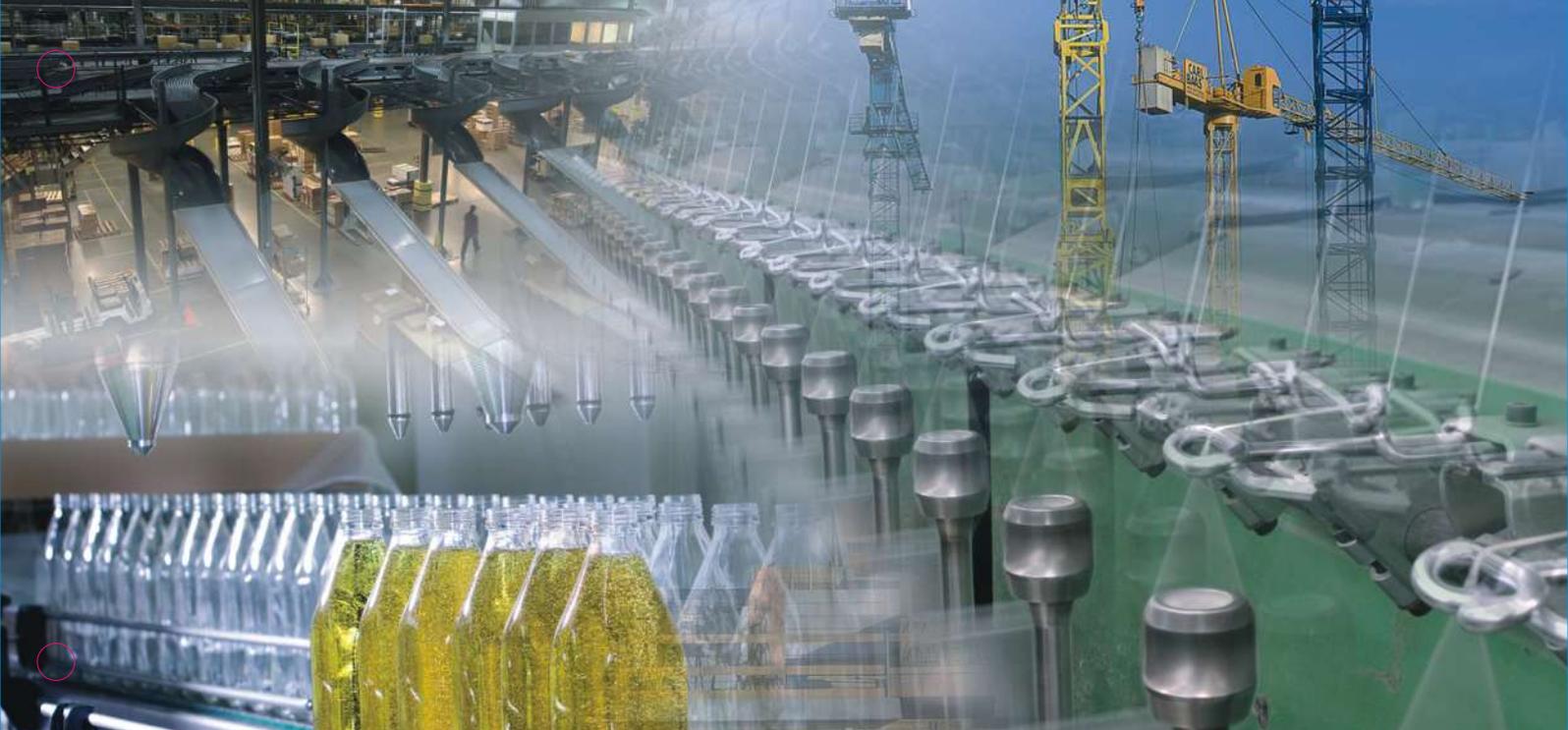


FRENIC
MEGA



Maximum Engineering for Global Advantage

3-phase 400 V 0.4 to 630 kW

High Performance Multifunctional Inverter



The performance reaching the peak in the industry

FRENIC-MEGA is a high performance, multifunctional inverter Fuji Electric has developed by gathering the best of its technologies.

Now it is ready to answer your needs.

Maximum Engineering for Global Advantage

What is FRENIC-MEGA and what are the advantages?

- Able to drive induction and permanent magnet synchronous motors
- Built-in EMC filter as standard
- STO compliant to EN 61800-5-2 SIL 2 and EN ISO 13849-1 PL d Cat. 3
- Ability to handle up to 3 simultaneous option cards (3 ports)
- Keypad with a USB connector
- Built-in braking transistor up to 22 kW (standard) and 160 kW (option)
- Safety enable input
- Full network support
- 4 complete motor maps

Improved control performance

Motor control methods: PG vector control, sensorless vector control, dynamic torque vector control, and V/f control.

Improved performance of current response and speed response (vector control)

Improved durability in overload operation

- HD (high duty) spec: 200% for 3 sec / 150% for 1 min
- LD (low duty) spec: 120% for 1 min

Lower maintenance

Maintenance warning output signal

Use of parts with a longer life cycle

Best vector control for the general-purpose inverter in its class

Maximizing the performance of a general-purpose motor by using closed loop vector control

Effective in providing highly accurate control for applications such as offset printing, hoisting, winding and wire drawing

- Speed control range: 1:1500
- Speed response: 100 Hz
- Speed control accuracy: $\pm 0.01\%$
- Current response: 500 Hz
- Torque accuracy: $\pm 10\%$

Maximizing the performance of a general-purpose motor Sensorless vector control

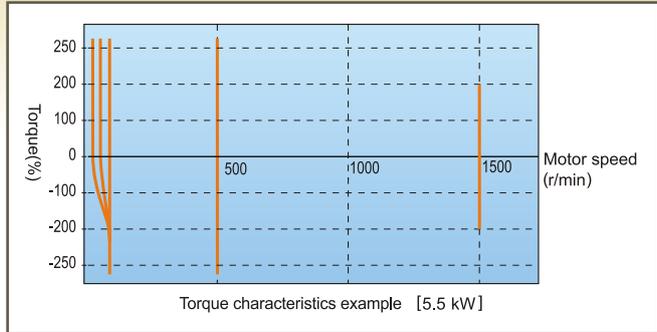
Useful for applications which require a high starting torque, such as mixers, extruders and conveyors

- Speed control range: 1:200
- Speed response: 20 Hz
- Speed control accuracy: $\pm 0.5\%$

- Current response: 500 Hz
- Torque accuracy: $\pm 10\%$
- Zero speed torque: $100\% \pm 20\%$

Fuji's original dynamic torque vector control has further evolved

Dynamic torque vector control has been improved to achieve a high starting torque of 200% even at a low-speed rotation of 0.3 Hz. This is a new method introduced by Fuji Electric.



Permanent magnet synchronous motor control

FRENIC-MEGA can drive permanent magnet synchronous motors, both sensorless (open loop) and with speed feedback (closed loop).

Improved durability during overload condition

The inverter performs short-time acceleration and deceleration with the maximum capacity by achieving better time rating of the overload ratings compared with our previous models. This improves the operation efficiency of the equipment such as a cutting machine or conveyors.

Overload capability: 200% for 3 sec. and 150% for 1 min.

The standard model is available in two specifications concerning the operation load.

Classification	Overload current rating	Major use
HD (High duty) spec	200% for 3 sec, 150% for 1 min	Operation under heavy load
LD (Low duty) spec	120% for 1 min	Operation under light load

Expanded capacity for the brake circuit built-in models

A brake circuit is built in the 22 kW or smaller models as a standard feature. These inverters are suitable to be used in machines with regenerative load such as vertical conveyance machines. The 7.5 kW or smaller models also incorporate a braking resistor

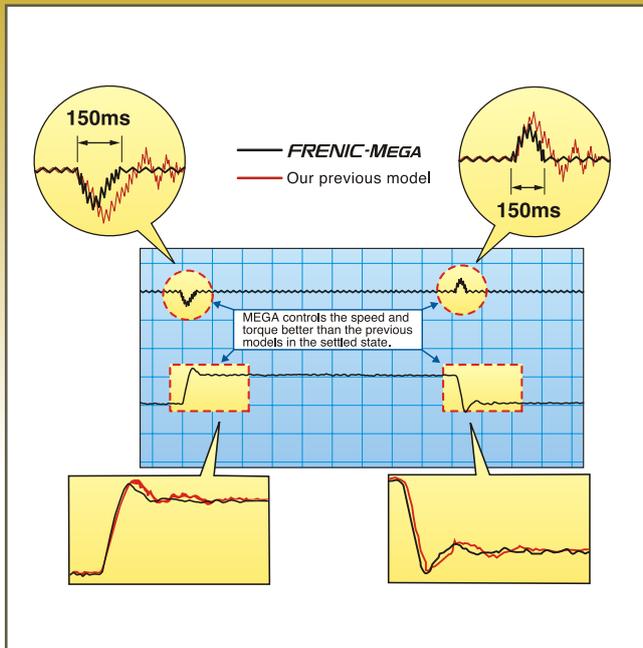
From 30 kW to 160 kW models in 400 V series built-in brake circuit can be manufactured on request.

Dedicated brake control function

Torque values are now included in the brake releasing conditions, which ensures that motor torque is generated, and therefore brake signal is more reliable.

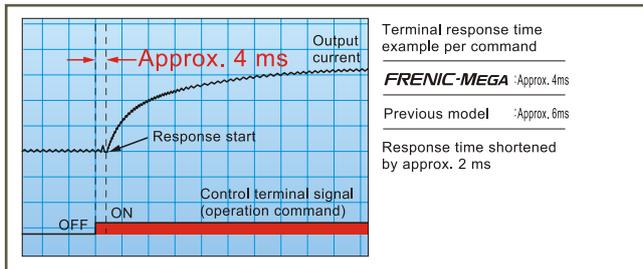
Improved reaction to the fluctuation of impact load

When a large load fluctuation occurs, the inverter provides the fastest torque response in its class. It controls the flux to minimize the fluctuation in the motor speed while suppressing the vibration. This function is best suited for the equipment that requires stable speed such as a cutting machine.



Quicker response to the operation commands

The terminal response to the operation commands has had an established reputation. FRENIC-MEGA has further shortened this response time, achieving the industry-top response time. This function is effective in shortening the time per cycle and effective for use in the process including frequent repetitions.



Double rating

HD (High Duty) Specification

- Overload capacity 150% 1min 200% 3s
- Inverter capacity = Motor capacity
- General use

LD (Low Duty) Specification

- Overload capacity 120% 1min
- The motor capacity can be one size larger than the inverter capacity
- For application with light load (fans, pumps or centrifugal machines)

Support for simple maintenance and Improved working efficiency

Basic keypad TP-E1U

Built-in USB port (mini B connector): allows easy connection of a personal computer equipped with loader software.

Able to save:

- 1 complete function data set.
- Inverter operation data.

When this keypad is connected to the inverter, all the Loader software features can be used:

- Editing, comparing, and copying the function code data
- Real-time operation monitor
- Alarm history (indicating the latest four alarms)
- Maintenance information
- Real time trace
- Historical trace



Can be disconnected from the inverter and used standalone, connecting the keypad to a personal computer equipped with loader software (using USB connection), allowing to check the data saved in the keypad away from the factory site (office).

Multifunction Keypad TP-G1-J1

Features

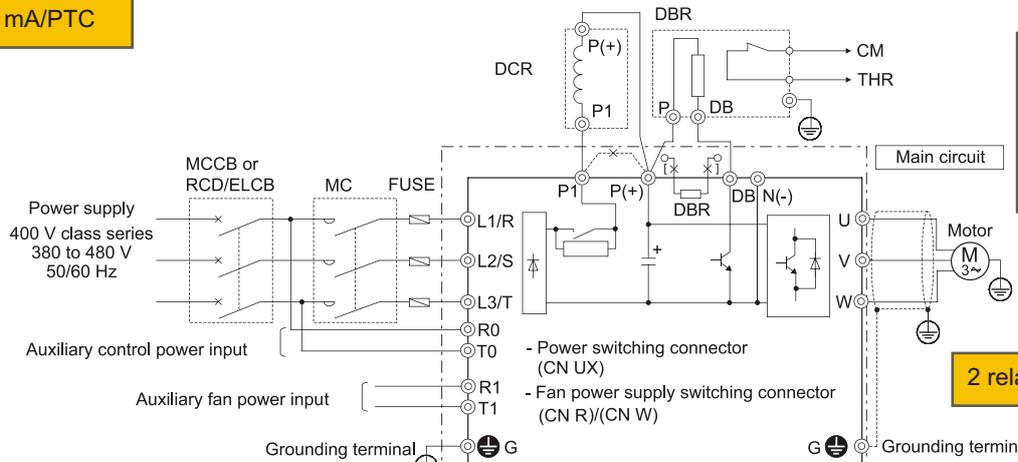
- LED and LCD display
- Function description in clear text (multi languages)
- Able to save 3 complete function sets
- Compatible with FRENIC Eco and FRENIC Multi
- Menu 0 can be defined
- I/O Check menu
- Operation monitor menu
- Communications debug menu



Wiring diagram

3 analog inputs:
 1: ± 10 VDC
 2: ± 10 VDC
 3: 4-20 mA/PTC

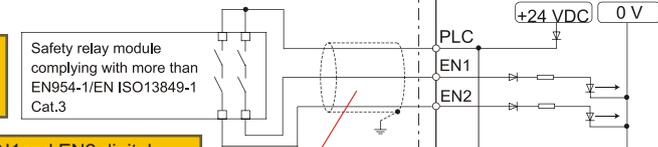
For further information about connecting the motor cable shield, please refer to FRENIC-MEGA Instruction Manual, Chapter 9.3 "Compliance with EMC Standards".



2 relay digital outputs

Analog input

- Potentiometer power supply
- Voltage input for frequency setting 0 to +10 VDC (0 to ±10 VDC)
- Voltage input for frequency setting 0 to ±10 VDC
- Current input for frequency setting 4 to 20 mA DC



Enable digital input (always SOURCE)

EN1 and EN2 digital inputs belong to STO function (always in SOURCE configuration)

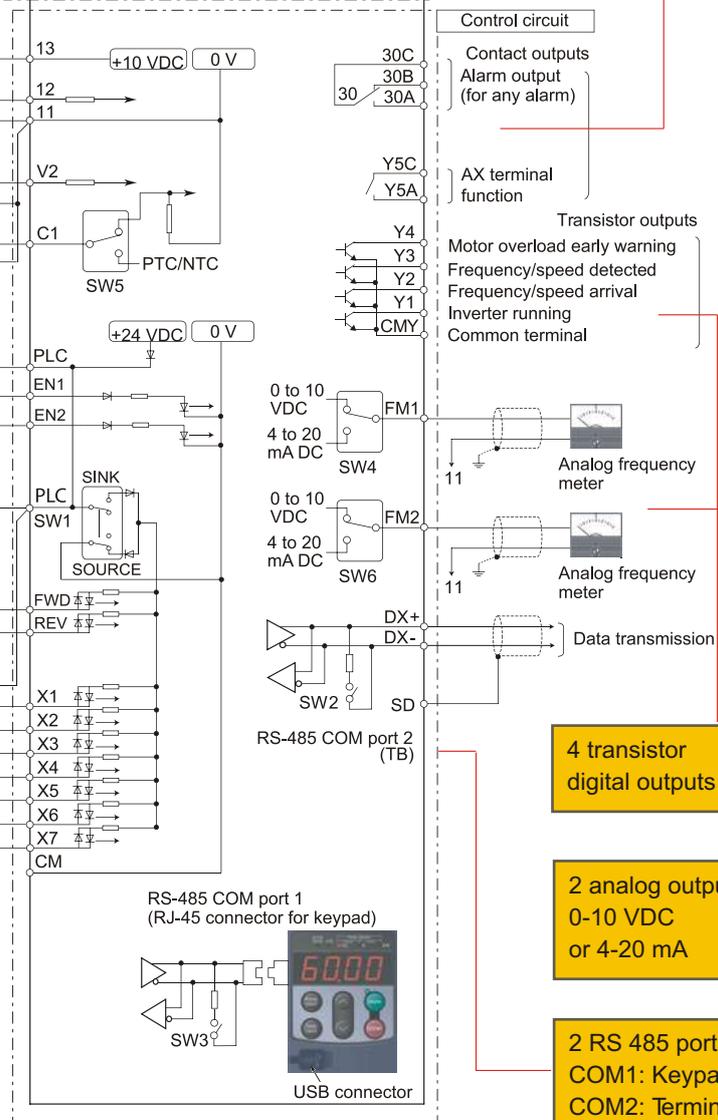
Digital input

- Run forward command
- Run reverse command
- Digital input common terminal
- Select multi-frequency (0 to 1 step)
- Select multi-frequency (0 to 3 step)
- Select multi-frequency (0 to 7 step)
- Select multi-frequency (0 to 15 step)
- Select ACC/DEC time (2 steps)
- Select ACC/DEC time (4 steps)
- Reset alarm
- Digital input common terminal

- DBR : Dynamic Braking Resistor
- DCR : DC Reactor
- RCD : Residual-current-operated protective device
- ELCB : Earth Leakage Circuit Breaker
- MC : Magnetic Contactor
- MCCB : Molded Case Circuit Breaker

9 digital inputs (SINK or SOURCE configurable)

X7: Pulse train digital input (std, 100 kpps)



4 transistor digital outputs

2 analog outputs:
 0-10 VDC
 or 4-20 mA

2 RS 485 ports:
 COM1: Keypad
 COM2: Terminals

Prolonged service life and improved life judgment function

Designed life 10 years

For the various consumable parts inside the inverter, their designed lives have been extended to 10 years, which also reduces maintenance downtime.

- Main circuit capacitor: 10 years
- Electrolytic capacitor on PCB: 10 years
- Cooling fan: 10 years

The parts life is estimated on condition that the inverter is used at an ambient air temperature of 40°C and under the load rate of 100%(HD spec) or 80%(LD spec).

Full support of life warnings

The inverter is loaded with the functions for facilitating the maintenance of the equipment.

Consideration for environment

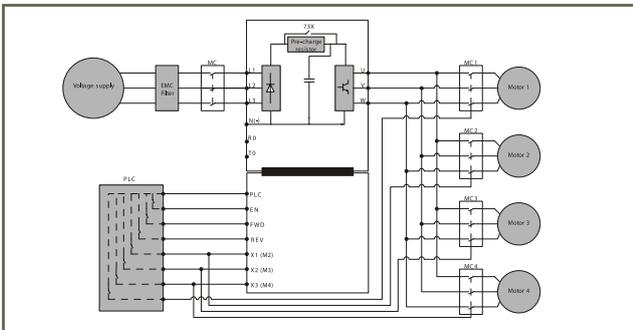
Enhanced resistance to environmental impact

Resistance to the environmental impact has been enhanced compared with conventional inverters.

- (1) Enhanced durability of the cooling fan, reducing environmental impact
- (2) Adoption of copper bars plated with nickel (Ni) or tin (Sn)

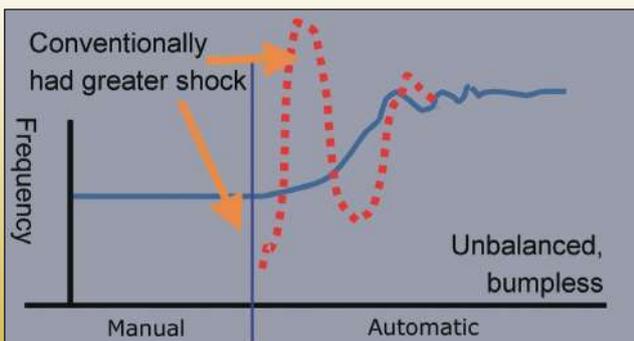
4 complete motor maps

Each motor (1-4), can be configured by its own function group, and the control mode for each motor (1-4) can be selected independently. Each motor can also be tuned independently.

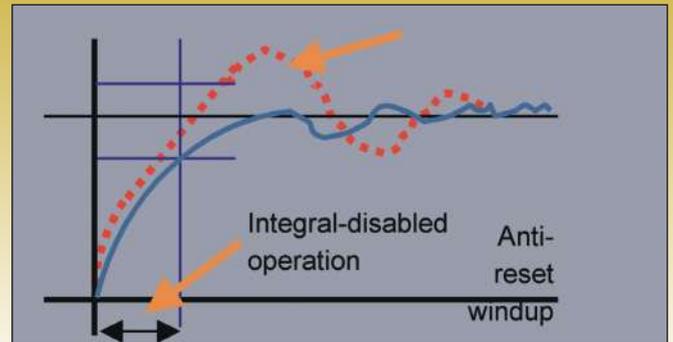


Complete PID control functions

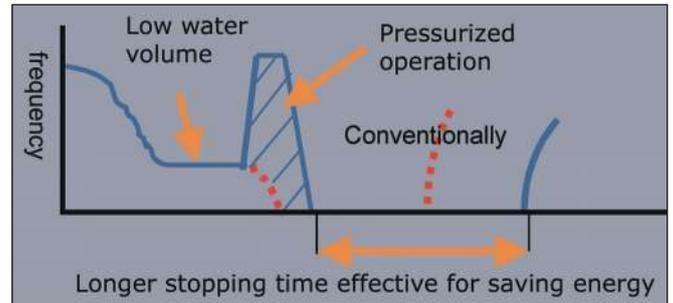
1. Unbalanced, bumpless function



2. Anti-reset windup function has been added



3. Stops operation at a slow flow rate



Servo lock function

- The inverter holds the position of the motor shaft
- Only available when using speed feedback (closed loop)
- To activate servo lock function, a digital input programmed with (LOCK) function must be active
- The inverter can indicate servo lock completion by a digital output programmed with (PSET) function

Loader Software

- Efficient data management: editing, comparing or copying function code data
- Test run, motor auto-tuning: aid at startup
- Operation monitor, real-time and historical tracing, failure monitor, multi-monitor: aid for maintenance and defect analysis
- Operation on Windows 2000, XP, Vista and Windows 7 guaranteed

Fieldbus Options

- ProfiBus DP interface
- CANopen interface
- DeviceNet interface
- T-Link interface
- SX Bus interface
- CC-link interface
- Etc.

Standard Specifications 3ph 400 V series

(0.4 to 55 kW)

Item		Specifications															
Type (FRN□□□G1E-4E)		0.4	0.75	1.5	2.2	4.0	5.5	7.5	11	15	18.5	22	30	37	45	55	
Nominal applied motor [kW] (*1) HD		0.4	0.75	1.5	2.2	4.0	5.5	7.5	11	15	18.5	22	30	37	45	55	
Nominal applied motor [kW] (*1) LD		—	—	—	—	—	7.5	11	15	18.5	22	30	37	45	55	75	
Output ratings	Rated capacity [kVA] (*2)	1.1	1.9	2.8	4.1	6.8	10	14	18	24	29	34	45	57	69	85	
	Rated voltage [V] (*3)	Three-phase 380 to 480 V (with AVR)															
	Rated Current [A] HD	1.5	2.5	4	5.5	9	13.5	18.5	24.5	32	39	45	60	75	91	112	
	Rated Current [A] LD	—	—	—	—	—	16.5	23	30.5	37	45	60	75	91	112	150	
	Overload capability	150% for 1 min, 200% for 3.0 s (HD) / 120% for 1 min (LD)															
Rated frequency [Hz]	50, 60 Hz																
Input ratings	Main circuit power Phases, voltage, frequency	Three-phase 380 to 480 V, 50/60 Hz															
	Auxiliary control power input Phases, voltage, frequency	—	Single-phase 380 to 480 V, 50/60 Hz														
	Auxiliary power input for fan Phases, voltage, frequency (*5)	—															
	Voltage, frequency variations	Voltage: +10 to -15% (Voltage unbalance: 2% or less (*6)) Frequency: +5 to -5%															
	Rated current [A] (*7) HD	with DCR	0.85	1.6	3.0	4.5	7.5	10.6	14.4	21.1	28.8	35.5	42.2	57.0	68.5	83.2	102
		without DCR	1.7	3.1	5.9	8.2	13.0	17.3	23.2	33	43.8	52.3	60.6	77.9	94.3	114	140
Required power supply capacity [kVA] (*8) HD	with DCR	0.6	1.2	2.1	3.2	5.2	7.4	10	15	20	25	30	40	48	58	71	
	without DCR	—	—	—	—	—	14.4	21.1	28.8	35.5	42.2	57.0	68.5	83.2	102	138	
Rated current [A] (*7) LD	with DCR	—	—	—	—	—	23.2	33.0	43.8	52.3	60.6	77.9	94.3	114	140	—	
	without DCR	—	—	—	—	—	10	15	20	25	30	40	48	58	71	96	
Braking	Torque [%] (*9)	150%			100%				20%				10 to 15%				
	Braking transistor	Built-in															
	Min. ohmic value [Ω]	200			160			96		64		32		24		16	
	Torque [%]	180%			180%			180%		180%		180%		180%		—	
	Built-in braking resistance		720Ω	470Ω	160Ω				80Ω				—				
		Braking time[s]	5 s														
%ED	5			3			5		3		2		3		2		
DC injection braking	Starting frequency: 0.0 to 60.0 Hz, Braking time: 0.0 to 30.0 s, Braking level: 0 to 100%																
EMC filter	EMC standard compliance: Category C3 is only emission and 2nd Env. is immunity. (EN61800-3:2004)																
DC reactor (DCR)	Optional																
Applicable safety standards	UL508C, C22.2No.14, EN50178:1997																
Enclosure (IEC60529)	IP20(IEC60529) closed type, UL open type (UL 50)											IP00 open type, UL open type					
Cooling method	Natural cooling					Fan cooling											
Weight/Mass [kg]	1.8	2.1	2.7	2.9	3.2	6.8	6.9	6.2	10.5	10.5	11.2	26	27	32	33		

(75 to 630 kW)

Item		Specifications															
Type (FRN□□□G1E-4E)		75	90	110	132	160	200	220	280	315	355	400	500	630			
Nominal applied motor [kW] (*1) HD		75	90	110	132	160	200	220	280	315	355	400	500	630			
Nominal applied motor [kW] (*1) LD		90	110	132	160	200	220	280	355	400	450	500	630	710			
Output ratings	Rated capacity [kVA] (*2)	114	134	160	192	231	287	316	396	445	495	563	731	891			
	Rated voltage [V] (*3)	Three-phase 380 to 480 V (with AVR)															
	Rated Current [A] HD	150	176	210	253	304	377	415	520	585	650	740	960	1170			
	Rated Current [A] LD	176	210	253	304	377	415	520	650	740	840	960	1170	1370			
	Overload capability	150% for 1 min, 200% for 3.0 s (HD) / 120% for 1 min (LD)															
Rated frequency [Hz]	50, 60 Hz																
Input ratings	Main circuit power Phases, voltage, frequency	Three-phase 380 to 440 V / 50 Hz Three-phase 380 to 480 V / 60 Hz															
	Auxiliary control power input Phases, voltage, frequency	Single-phase 380 to 480 V, 50/60 Hz															
	Auxiliary power input for fan Phases, voltage, frequency (*5)	Single-phase 380 to 440 V / 50 Hz Single-phase 380 to 480 V / 60 Hz															
	Voltage, frequency variations	Voltage: +10 to -15% (Voltage unbalance: 2% or less (*6)) Frequency: +5 to -5%															
	Rated current [A] (*7) HD	with DCR	138	164	201	238	286	357	390	500	559	628	705	881	1115		
		without DCR	—	—	—	—	—	—	—	—	—	—	—	—	—		
Required power supply capacity [kVA] (*8) HD	with DCR	96	114	140	165	199	248	271	347	388	436	489	611	773			
	without DCR	—	—	—	—	—	—	—	—	—	—	—	—	—			
Rated current [A] (*7) LD	with DCR	164	210	238	286	357	390	500	628	705	789	881	1115	1256			
	without DCR	—	—	—	—	—	—	—	—	—	—	—	—	—			
Required power supply capacity [kVA] (*8) LD	with DCR	114	140	165	199	248	271	347	436	489	547	611	773	871			
Braking	Torque [%] (*9)	10 to 15%															
	Braking transistor	—															
	Min. ohmic value [Ω]	—															
	Torque [%]	—															
DC injection braking	Starting frequency: 0.0 to 60.0 Hz, Braking time: 0.0 to 30.0 s, Braking level: 0 to 100%																
EMC filter	EMC standard compliance: Category C3 is only emission and 2nd Env. is immunity. (EN61800-3:2004)																
DC reactor (DCR)	Optional (must be installed)																
Applicable safety standards	UL508C, C22.2No.14, EN50178:1997, EN 61800-5-2 SIL 2 and EN ISO 13849-1 PL d Cat. 3																
Enclosure (IEC60529)	IP00 open type, UL open type																
Cooling method	Fan cooling																
Weight/Mass [kg]	42	62	64	103	103	144	144	245	245	330	330	530	530				

(*1) Fuji's 4-pole standard motor

(*2) Rated capacity is calculated by assuming the output rated voltage as 220 V for three-phase 200 V series and 440 V for three-phase 400 V series.

(*3) Output voltage cannot exceed the power supply voltage.

(*5) The auxiliary power input is used as an AC fan power input when combining the unit such as high power factor PWM converter with power regenerative function. (Generally not used.)

(*6) Interphase voltage unbalance ratio [%] = (max. voltage [V] - min. voltage [V]) / 3-phase average voltage [V] × 67 (See IEC61800-3.) Use the DC reactor (ACR: optional) when used with 2 to 3 % of unbalance ratio.

(*7) The value is calculated on assumption that the inverter is connected with a power supply capacity of 500kVA (or 10 times the inverter capacity if the inverter capacity exceeds 50kVA) and %X is 5%.

(*8) Obtained when a DC reactor (DCR) is used.

(*9) Average braking torque obtained by use of a motor. (Varies with the efficiency of the motor.)



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